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Auffinden von Nebenläufigkeitsfehlern durch statische Codeanalyse

Royd Lüdtke
Verifysoft Technology GmbH
luedtke@verifysoft.com
+49 781 127 8118-8

Agenda

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- Was ist Nebenläufigkeit?
- Was ist Parallelisierung?
- Zuweisung von CPU-Zeit durch den Scheduler
- Motivation zur Implementierung von Nebenläufigkeit?
- Was sind Nebenläufigkeitsfehler?
- Warum sind Nebenläufigkeitsfehler so gefürchtet?
- Beispiel Data Race
- Beispiel Dead Lock (Nested Lock)
- Wie kann die statische Codeanalyse helfen?

Nebenläufigkeit - Parallelisierung

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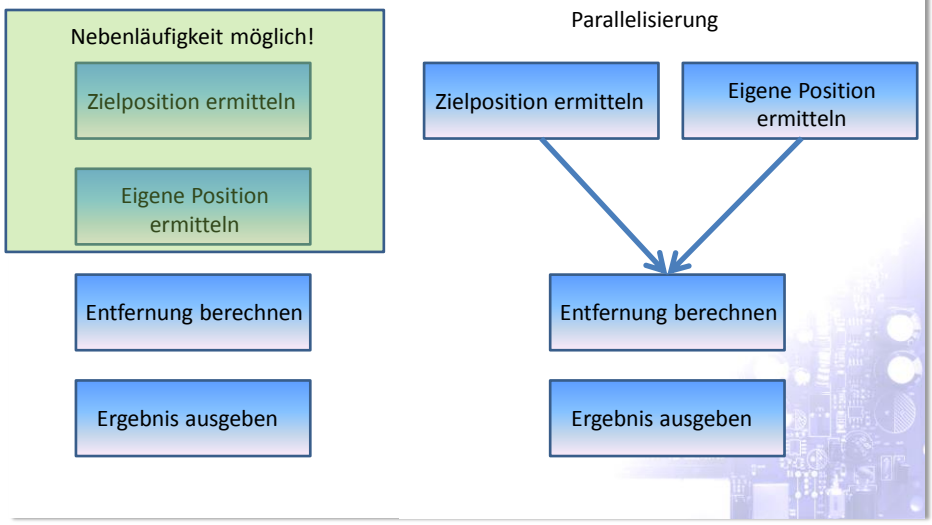

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Thread - Scheduler

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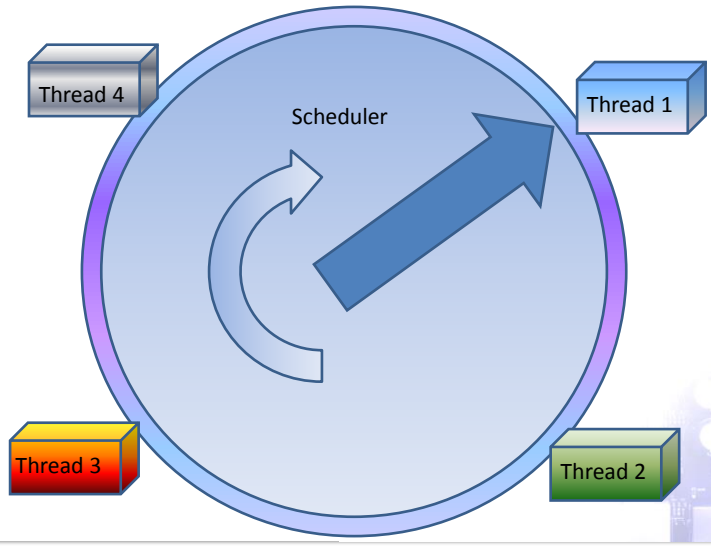

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Motivation zur Implementierung von Nebenläufigkeit

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Multicore Mikrocontroller (Auswahl)

Hersteller	Typ	Cores	Bitness
XMOS	L-Serie	4 - 16	64
Freescale	MPC5777M MCU	4	32
Infinion	AURIX™ Family – TC29xT	3	32
STMicroelectronics	SPC56EL70	2	32
Parallax	Propeller	8	32

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Multithreaded Programming Model

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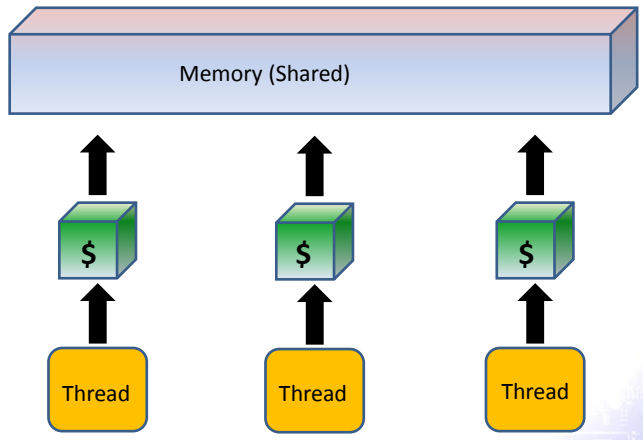

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Was sind Nebenläufigkeitsfehler ?

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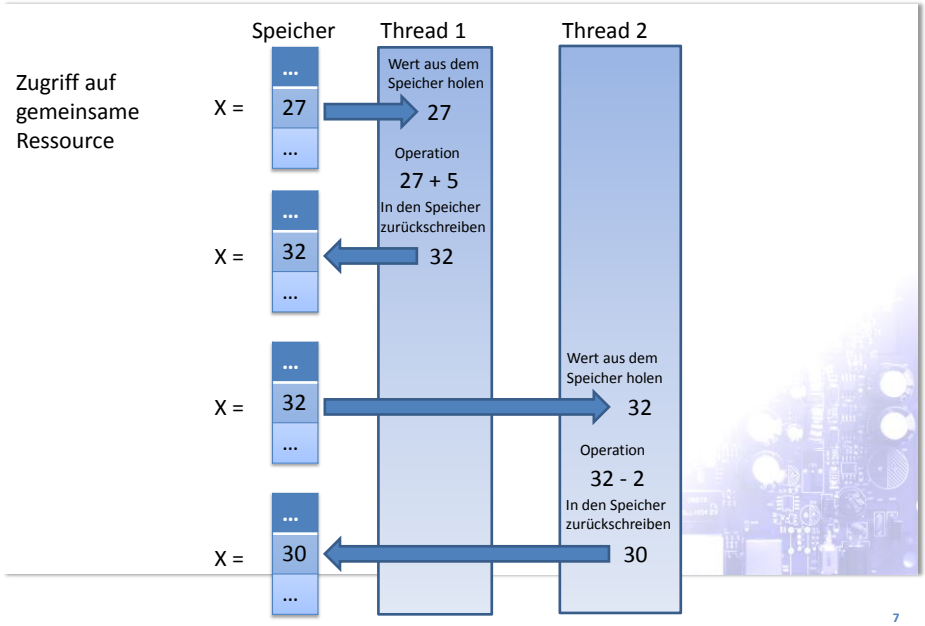

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Was sind Nebenläufigkeitsfehler ?

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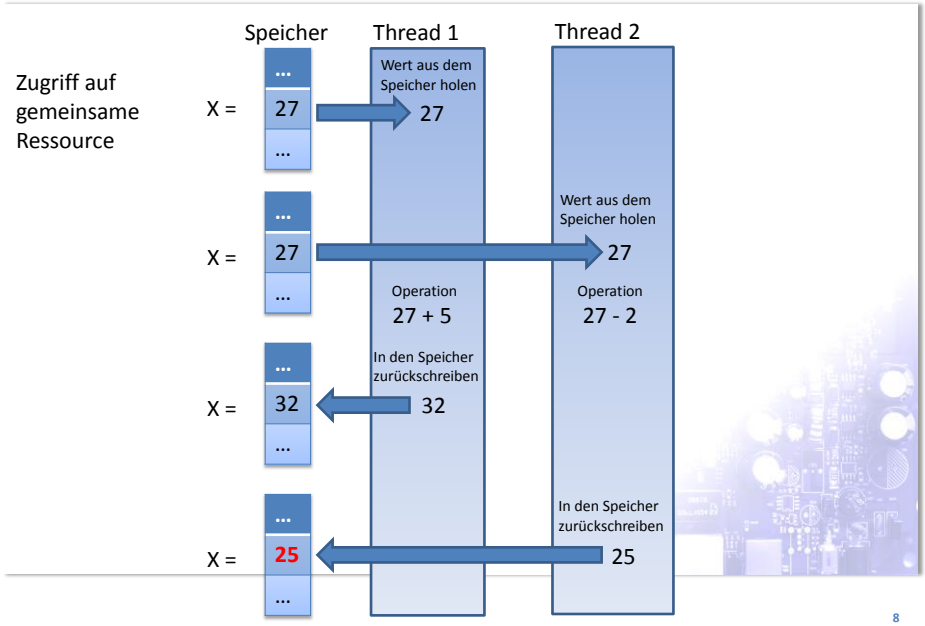

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Warum sind Nebenläufigkeitsfehler so gefürchtet ?

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Problematik des Auffindens zur Laufzeit

- In der Regel kein deterministisches Auftreten
- Verhalten oft lastabhängig
- Einsatz von Prüfwerkzeugen (z. B. Debugger) ändert das Laufzeitverhalten oft derart, dass der Fehler nicht mehr auftritt

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Heisenbergsche Unschärferelation

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$$\Delta x * \Delta p \sim h$$

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Beispiel: Data Race

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```
int main(void){
   DWORD   threadId_1, threadId_2;
   HANDLE  threadHandle_1, threadHandle_2;
   unsigned long segment_info0[3] = { 0, 5000000, 10000000 };
   unsigned long segment_info1[3] = { 5000001, 10000000, 10000000 };

   threadHandle_1 = CreateThread(NULL, 0, &calculate, (LPVOID)segment_info0, 0, &threadId_1);
   if (threadHandle_1 == NULL) {
          exit(EXIT_FAILURE);
   }
   threadHandle_2 = CreateThread(NULL, 0, &calculate, (LPVOID)segment_info1, 0, &threadId_2);
   if (threadHandle_2 == NULL) {
          exit(EXIT_FAILURE);
   }

   WaitForSingleObject(threadHandle_1, INFINITE);
   WaitForSingleObject(threadHandle_2, INFINITE);

   CloseHandle(threadHandle_1);
   CloseHandle(threadHandle_2);

   printf("PI = %25.20lf\n", sum / segment_info0[2]);

   return 0;
}
```

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Fehlende Synchronisierung -> Data Race

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```
double sum;

DWORD WINAPI calculate(LPVOID params){
   double d, w;
   unsigned long l;
   unsigned long *part;

   part = (unsigned long*)params;
   d = 1.0 / part[2];
   for (l = part[0]; l < part[1]; ++l){
        w = d * (l + 0.5);
        sum += 4.0 / (1.0 + w * w);
   }
   return 0;
}
```

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Data Race – Lösung: Synchronisierung

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```
double sum;
CRITICAL_SECTION lock;

DWORD WINAPI calculate(LPVOID params){
   double d, w;
   unsigned long l;
   unsigned long *part;

   InitializeCriticalSection(&lock);
   part = (unsigned long*)params;
   d = 1.0 / part[2];
   for (l = part[0]; l < part[1]; ++l){
        w = d * (l + 0.5);
        EnterCriticalSection(&lock);
        sum += 4.0 / (1.0 + w * w);
        LeaveCriticalSection(&lock);
   }
   DeleteCriticalSection(&lock);
   return 0;
}
```

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Aufdeckung durch statische Codeanalyse

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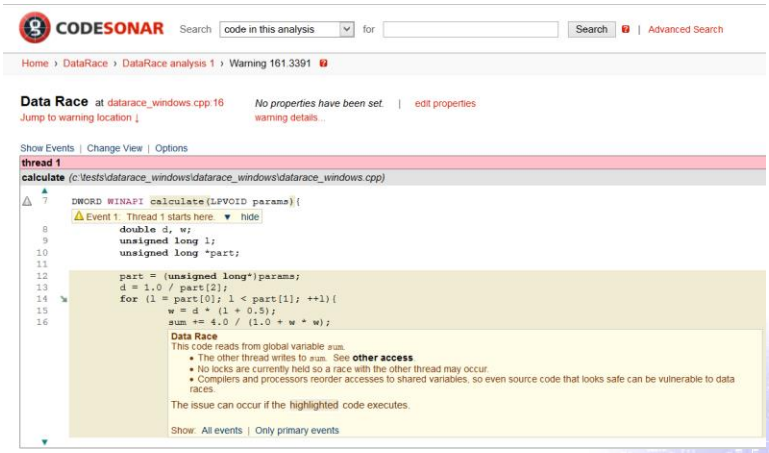

Deadlock-Situation

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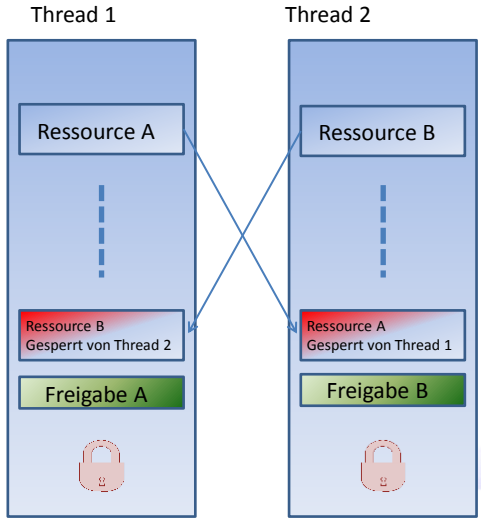

Typische Deadlock-Konstellation

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Thread 1:

```
lock(A);
lock(B);
unlock(B);
unlock(A);
```

Thread 2:

```
lock(B);
lock(A);
unlock(A);
unlock(B);
```

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Nested Lock

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```
DWORD WINAPI calculate_1(LPVOID params){
   double d, w;
   unsigned long l;
   unsigned long *part;

   InitializeCriticalSection(&lock_1);
   InitializeCriticalSection(&lock_2);
   part = (unsigned long*)params;
   d = 1.0 / part[2];
   for (l = part[0]; l < part[1]; ++l){
        w = d * (l + 0.5);
        EnterCriticalSection(&lock_1);
        EnterCriticalSection(&lock_2);
        sum += 4.0 / (1.0 + w * w);
        LeaveCriticalSection(&lock_2);
        LeaveCriticalSection(&lock_1);
   }
   DeleteCriticalSection(&lock_1);
   DeleteCriticalSection(&lock_2);
   return 0;
}
```

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Nested Lock

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```
DWORD WINAPI calculate_2(LPVOID params){
    double d, w;
    unsigned long l;
    unsigned long *part;

    InitializeCriticalSection(&lock_1);
    InitializeCriticalSection(&lock_2);
    part = (unsigned long*)params;
    d = 1.0 / part[2];
    for (l = part[0]; l < part[1]; ++l){
        w = d * (l + 0.5);
        EnterCriticalSection(&lock_2);
        EnterCriticalSection(&lock_1);
        sum += 4.0 / (1.0 + w * w);
        LeaveCriticalSection(&lock_1);
        LeaveCriticalSection(&lock_2);
    }
    DeleteCriticalSection(&lock_1);
    DeleteCriticalSection(&lock_2);
    return 0;
}
```

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Aufdeckung durch statische Codeanalyse

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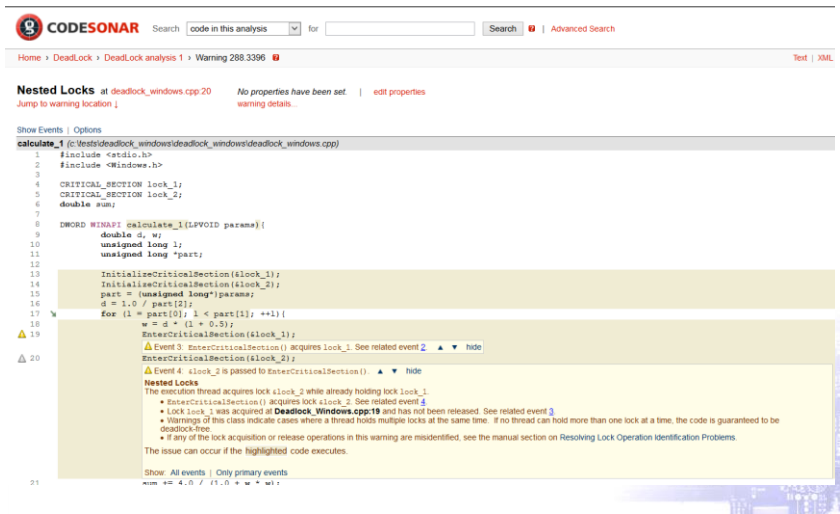

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VIELEN DANK !
Royd Lüdtke
Verifysoft Technology GmbH
luedtke@verifysoft.com
+49 781 127 8118-8